

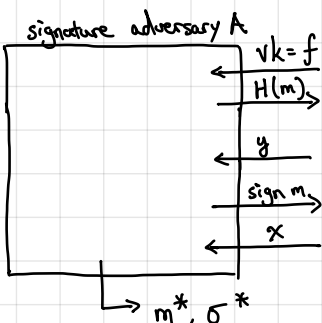
Proof Sketch:

one-wayness adversary B

challenger

$$y^* \xleftarrow{R} y$$

assume A queries H on m before making signing query on m



- will program  $y^*$  to  $i^*$  query to H ( $i^*$  is a random index)

if this is query  $i^*$ :  $y \leftarrow y^*$

else,  $x \leftarrow D$ ,  $y \leftarrow f(x)$ , add  $m \mapsto (x, y)$  to table

if  $m \mapsto (x, y)$  is present in table, reply with  $x$  otherwise abort

if  $m^*$  is query  $i^*$ , then output  $\sigma^*$  otherwise abort

If A makes Q random oracle queries, B succeeds with probability  $\frac{1}{Q} \cdot \text{SigAdv}[A]$ .

- All random oracle queries are properly distributed (since forward sampling and reverse sampling are statistically indistinguishable)
- All signature queries are properly distributed (as long as guess is correct)
- Guess is correct with prob.  $\frac{1}{Q}$
- If guess is correct and A succeeds, then  $f(\sigma^*) = H(m^*) = y^*$  so B succeeds.

Constructing preimage sampleable trapdoor functions from SIS.

$$f_A(x) := Ax \pmod{q} \quad [A \in \mathbb{Z}_q^{n \times m}, x \in \mathbb{Z}_q^m]$$

Goal: given a target vector  $y \in \mathbb{Z}_q^n$ , sample  $x \in \mathbb{Z}^m$  such that  $Ax = y$

Recall the SIS lattice

$$\mathcal{L}^\perp(A) = \{x \in \mathbb{Z}^m : Ax = 0 \pmod{q}\}$$

For a vector  $u \in \mathbb{Z}_q^n$ , recall that the coset  $\mathcal{L}_u^\perp(A)$  is

$$\mathcal{L}_u^\perp(A) = c + \mathcal{L}^\perp(A) = \{x \in \mathbb{Z}^m : Ax = u\}$$

$\leftarrow c \in \mathbb{Z}_q^m$  is an arbitrary vector where  $Ac = u$

} Equivalent formulation of objective: sample from some "nice" distribution over  $\mathcal{L}_u^\perp(A)$

Challenge: Defining a distribution over  $\mathcal{L}_u^\perp(A)$  that is conducive for preimage sampling.

- Sampling preimages (given a trapdoor) must be efficient
- Samples must not leak trapdoor (can be simulated without knowledge of trapdoor)

The distribution is typically a discrete Gaussian distribution - shares many analytical properties with continuous Gaussians

Definition: For a parameter  $s > 0$ , we define the Gaussian function on  $\mathbb{R}^n$  with width  $s$  as follows:

$$p_s(x) := \exp(-\pi \|x\|^2 / s^2)$$

$$p_{s,c}(x) := \exp(-\pi \|x - c\|^2 / s^2)$$

Gaussian centered at  $c \in \mathbb{R}^n$

Discrete Gaussian centered at  $c$ :

$$D_{L,s,c}(x) \propto \begin{cases} p_{s,c}(x) & x \in L \\ 0 & \text{otherwise} \end{cases}$$

proportional to

$$D_{L,s,c}(x) = \frac{p_{s,c}(x)}{\sum_{x \in L} p_{s,c}(x)} = \frac{p_{s,c}(x)}{p_{s,c}(L)}$$

normalization parameter

Why discrete Gaussian distribution?

Nicely behaved:

- Rotationally invariant over  $\mathbb{R}^n$ :

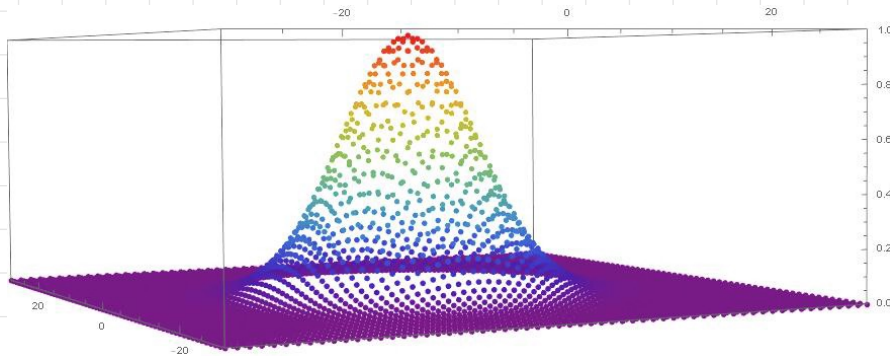
$$p_s(\vec{x}) = \prod_{i=1}^n p_s(x_i)$$

(density depends only on the norm  $\|x\|$  of input)

- Sum of Gaussians is Gaussian (Gaussian convolution lemma)

Algorithms leverage these properties

Visually (2D setting) for  $\mathbb{Z}^2$ :



Here, we sketch one approach for discrete Gaussian sampling based on gadget trapdoors + perturbation [MP12, GPV08, Pei10]

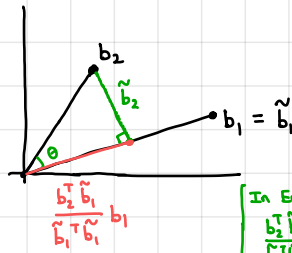
We start by recalling the Gram-Schmidt orthogonalization method from linear algebra

- Let  $b_1, \dots, b_n \in \mathbb{R}^d$  be a collection of vectors with  $\text{span}(b_1, \dots, b_n) = V$  [ $b_1, \dots, b_n$  need not be linearly independent]
- The Gram-Schmidt orthogonalization process outputs  $\tilde{b}_1, \dots, \tilde{b}_n \in \mathbb{R}^d$  where  $\text{span}(\tilde{b}_1, \dots, \tilde{b}_n) = V$  and  $\tilde{b}_i^T \tilde{b}_j = 0$  for all  $i \neq j$

Algorithm:  $\tilde{b}_1 \leftarrow b_1$

for each  $i = 2, \dots, n$ :

$$\tilde{b}_i \leftarrow b_i - \sum_{j < i} \underbrace{\frac{b_i^T \tilde{b}_j}{\tilde{b}_j^T \tilde{b}_j}}_{\text{projection of } b_i \text{ onto } \tilde{b}_j} \cdot \tilde{b}_j$$



$$\left[ \text{In Euclidean space: } \frac{b_2^T \tilde{b}_1}{\tilde{b}_1^T \tilde{b}_1} \tilde{b}_1 = \frac{\|b_2\| \cdot \|\tilde{b}_1\| \cos \theta}{\|\tilde{b}_1\|^2} \tilde{b}_1 = \text{projection of } b_2 \text{ onto } \tilde{b}_1 \right]$$

Not difficult to show that  $\tilde{b}_1, \dots, \tilde{b}_n$  are pairwise orthogonal

- Let  $\tilde{B} = [\tilde{b}_1 \dots \tilde{b}_n]$  be the Gram-Schmidt basis.

Important:  $B$  and  $\tilde{B}$  span the same vector space over  $\mathbb{R}$ , but do not necessarily generate the same lattice ( $\tilde{b}_i$  is not necessarily an integer linear combination of  $b_1, \dots, b_n$ )

Simple counter-example:  $b_1 = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$   $b_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$   
 $\tilde{b}_1 = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$   $\tilde{b}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$  observe that  $\tilde{b}_2 \notin \mathcal{L}(B)$

- The norm of the Gram-Schmidt vectors provides a bound on the minimum distance of a lattice:

$$\lambda_1(\mathcal{L}(\tilde{B})) \geq \min_{i \in [n]} \|\tilde{b}_i\|$$

Proof. Take any lattice point  $Bx \neq 0$  where  $x \in \mathbb{Z}^n$ . Let  $k$  be largest index where  $x_k \neq 0$ . Consider now the product

$$\begin{aligned} (Bx)^T \tilde{b}_k &= \sum_{i \leq k} x_i \tilde{b}_i^T \tilde{b}_k = x_k \tilde{b}_k^T \tilde{b}_k && \text{since } \tilde{b}_k \text{ is orthogonal to } b_1, \dots, b_{k-1} \text{ by construction} \\ &= x_k \|\tilde{b}_k\|^2 && \text{since } \tilde{b}_k^T \tilde{b}_k = \|\tilde{b}_k\|^2 \text{ also by construction} \end{aligned}$$

By Cauchy-Schwarz ( $|u^T v| \leq \|u\| \cdot \|v\|$ ), we now have

$$\begin{aligned} \|Bx\|_2 \cdot \|\tilde{b}_k\|_2 &\geq |(Bx)^T \tilde{b}_k| = |x_k| \cdot \|\tilde{b}_k\|^2 \geq \|\tilde{b}_k\|^2 && \text{since } x_k \in \mathbb{Z} \text{ and } x_k \neq 0 \\ &\geq \min_{i \in [n]} \|\tilde{b}_i\|. \end{aligned}$$